Chapter 3 Class Notes

Sections 3.1 and 3.2

- Recall, a random variable (RV) is a real-valued function defined over a sample space, S. A random variable Y is said to be discrete if it can take on only a <u>finite</u> or <u>countably infinite</u> number of distinct values.
- Uppercase Y is a random variable, and lowercase y is a particular value that the random variable may assume:
 <u>Y is random, y is not</u>. (Y = y) is to be understood as the set of points in S assigned to the value y by the RV Y.
- Def. 3.2. The probability that Y takes on the value y,
 P(Y = y), is defined as the <u>sum of the probabilities of all</u> sample points in S that are assigned to the value y.
 Often (usually), we write P(Y = y) as p(y).
- Def. 3.3 (p.88). The probability distribution for a discrete RV Y can be represented by a formula, a table, or a graph that provides p(y) = P(Y = y) for all y.
- Example 3.1 (p.88). From A = {M₁, M₂, M₃, W₁, W₂, W₃}, we choose just two. There are $\binom{6}{2}$ = 15 sample points in S; Y is the number of women selected. Here the probability distribution formula is $p(y) = \frac{\binom{3}{y}\binom{3}{2-y}}{\binom{6}{2}}$

for y = 0, 1, 2. For example, p(0) = 3/15 since there are 3 sample points in S that map to Y = 0, viz, M_1M_2 , M_1M_3 , M_2M_3 . The table and histogram are on p.89.

- Theorem 3.1 (p.89): for any discrete RV, we have:
 - $0 \le p(y) \le 1$ for all y
 - $\sum_{y} p(y) = 1$, where the sum here is over all values of y with nonzero probability
- <u>p.90, ex.3.7</u>: Y = # of empty bowls

У	P(y)	$y \times P(y)$	$y^2 \times P(y)$
0	2/9	0	0
1	6/9	6/9	6/9
2	1/9	2/9	4/9
Total	9/9 = 1	8/9	10/9

Section 3.3

• <u>Def. 3.4</u> (p.91): Y is a discrete RV with probability function p(y), then the expected value of Y, E(Y) is defined to be $E(Y) = \sum_y y P(y)$ (taken over all y with non-zero probability) – provided the sum is absolutely convergent, i.e., that $\sum_y |y| P(y) < \infty$

• Theorem 3.2 (p.93): Y is a discrete RV with probability function p(y) and g(Y) is a real-valued function of Y, then the expected value of g(Y) is:

$$E[g(Y)] = \sum_{y} g(y)p(y)$$

• Def. 3.5 (p.93). Y is a RV with mean E(Y) = μ , then the variance of Y is

$$\sigma^2 = E[(Y - \mu)^2]$$

The standard deviation (σ) is the positive square root of σ^2 . The units of μ and σ are the same as for y.

- Example 3.2. The table and histogram are given on p.94. We get μ = (0)(1/8) + (1)(2/8) + (2)(3/8) + (3)(2/8) = 14/8 = 7/4 = 1.75. Also, σ^2 = (0 1.75) 2 (1/8) + (1 1.75) 2 (2/8) + (2 1.75) 2 (3/8) + (3 1.75) 2 (2/8) = 7.5/8 = 0.9375, and so $\sigma = \sqrt{0.9375} = 0.9682$. Then, $\mu \pm \sigma$ is (0.7818,2.7182), which contains 5/8 = 0.625 of the probability mass, close to the empirical rule (68%)
- Theorems 3.3 3.5 (p.95) can be combined to say that for Y a discrete RV with probability function p(y) and a,b,c are constants, then $E(\bullet)$ is a linear operator: E[af(Y) + bg(Y) + c] = aE[f(Y)] + bE[g(Y)] + c
- Theorem 3.6 (p.96). Let Y be a RV with probability function p(y) and mean E(Y) = μ , then

$$\sigma^2 = E[Y^2] - \mu^2$$

(sometimes called the *short-cut formula* for σ^2)

- Example 3.2 continued. $E(Y^2) = (0^2)(1/8) + (1^2)(2/8) + (2^2)(3/8) + (3^2)(2/8) = 32/8 = 4$, so $\sigma^2 = 4 1.75^2 = 15/16$
- <u>p.90, ex.3.7 continued</u>. $\mu = E(Y) = 8/9$, $E(Y^2) = 10/9$ so $\sigma^2 = 10/9 (8/9)^2 = 26/81 = 0.3210 = 0.5666^2$
- p.99, ex.3.23 the table and calculations are as follows

У	P(y)	y × P(y)	$y^2 \times P(y)$
-4	9/13	-36/13	144/13
5	2/13	10/13	50/13
15	2/13	30/13	450/13
		μ = 4/13	$E(Y^2) = 644/13$

Here, $\sigma^2 = 644/13 - (4/13)^2 = 8356/169 = 7.0316^2$. So, each time you play, you expect to win \$4/13 = 0.3077 = about 31¢ give or take about \$7.

Section 3.4

- <u>Def. 3.6</u> (p.101). A <u>binomial experiment</u> has <u>all</u> of the following properties:
 - 1. The experiment consists of a fixed number n of trials
 - 2. Each trial results in either a "success" S or "failure" F
 - 3. The success probability p stays the same for all trials
 - 4. The trials are independent
 - 5.Y, the random variable, is the number of successes observed in the n trials

- Notice that just one violation above makes the RV not binomial: 3 draws <u>without replacement</u> from a hat containing 5 red chips and 10 green ones and counting the number of reds is not binomial. If sampling is done <u>with replacement</u>, then the RV would be binomial with n = 3 and p = ½; if we called a green chip a "success", this would be binomial with n = 3 and p = ½. Also, note that sampling until you get the 5th red chip is not binomial since n is not set a priori.
- <u>Def. 3.7</u> (p.103). The binomial RV Y based on n trials and with success probability p has the binomial probability distribution formula:

$$p(y) = {n \choose y} p^y (1-p)^{n-y}, y = 0, 1 ... n; 0 \le p \le 1$$

- Plots of the prob. histograms are given on p.104 of Bin(n=10,p=0.1), Bin(n=10,p=½) and Bin(n=20,p=½)
- Letting q = 1 p, notice that we get these probabilities
 from the binomial expansion:

$$1 = 1^{n} = (q + p)^{n} = {n \choose 0} p^{0} q^{n} + {n \choose 1} p^{1} q^{n-1}$$

$$+ {n \choose 2} p^{2} q^{n-2} + \dots + {n \choose n-1} p^{n-1} q^{1} + {n \choose n} p^{n} q^{0}$$

$$= P(0) + P(1) + \dots + P(n-1) + P(n)$$

• <u>p. 105, ex. 3.7</u>. In a lot of 5000 electrical fuses, 5% are bad, we take a sample of 5 fuses, and the probability of observing at least one defective is *approximately*

$$1 - p(0) = 1 - {5 \choose 0} (0.05)^0 (0.95)^5 = 0.2262$$

- The above solution is only approximate since one binomial condition is not truly met (that p stays the same across the "draws" since sampling is without replacement), but the approximation is very close
- The above calculations in R:

 Had we taken a sample of n = 20 fuses above and wanted the probability of at least 4 defective:

- p. 105, ex. 3.8. p = 0.30 (recovery rate) and n = 10 (sample taken) if we see y = 9 recoveries, we could calculate: P(9) + P(10) = 0.000144 that the probability of what we saw or more extreme is very small, this makes us doubt that p = 30%, and conclude that the new medication may have been significantly improved
- Theorem 3.7 (p.107). Let Y be a binomial RV with parameters n (trials) and p (success probability). Then $\mu = E(Y) = np$ and $\sigma^2 = V(Y) = npq$ for q = 1 p.
- Proofs of the above results are instructive and should be carefully worked through.
- <u>p. 105, ex. 3.8</u>. In a binomial setting with n = 20, we

observe y = 6 "successes" (whether the employee favors the new retirement policy). To estimate p, we can use the technique of maximum likelihood (ML) estimation: the likelihood here is

$$L(p) = p(y) = \binom{n}{y} p^y (1-p)^{n-y} \propto p^6 (1-p)^{14}$$

Maximizing the likelihood is equivalent to maximizing the log-likelihood – whence,

$$\frac{d}{dp}[6ln(p) + 14ln(1-p)] = \frac{6}{p} - \frac{14}{1-p}$$

So the ML estimate (MLE) is $\hat{p} = \frac{6}{20} = 0.30$

Section 3.5

- Related to the binomial distribution is the geometric distribution, where Y = # of 'tosses' for the first success
- <u>Def. 3.8</u> (p.115). A RV Y has the <u>Geometric probability</u> <u>distribution</u> with success probability p if and only if $p(y) = q^{y-1}p$ for $y = 1, 2, 3 ..., 0 \le p \le 1$
- The probability histogram for a geometric RV with p =
 1/2 on p.115
- p. 116, ex. 3.11. A "success" is engine malfunction during a one-hour period, p = 0.02, & we want the probability the engine survives two hours = P(Y ≥ 3) = 1 P(Y ≤ 2) = 1 p qp = 1 0.02 (0.02)(0.98) = 0.9604 Y = the # of one-hour intervals until the 1st malfunction

- Some other texts (and R) define the geometric RV to be the <u>number of failures until the first success</u> (Y*); noting that Y* = Y 1, in the above, we have P(Y ≥ 3) = P(Y* ≥ 2) = 1 P(Y* ≤ 1); in R, we get:
 1-pgeom(1,0.02)
 0.9604
- Theorem 3.8 (p.116). Y has the geometric distribution (i.e., our definition!) with success p, then

$$\mu = E(Y) = \frac{1}{p} \text{ and } \sigma^2 = V(Y) = \frac{1-p}{p^2}$$

- Again, the proofs are very instructive (need to use your geometric series, which are very important!)
- <u>p. 116, ex. 3.11 (continued)</u>. For the engine failure ex., $\mu = 1/0.02 = 50$, $\sigma^2 = 0.98/0.02^2 = 2450 = 49.5^2$, so we expect to wait 50 hours give or take 50 hours.
- <u>p.118</u>, <u>ex. 3.13</u>. In a geometric setting with unknown p, the first person who likes the policy (success) is the 5th one interviewed, and we again use ML estimation:

$$L(p) = p(y) = (1-p)^{y-1}p = (1-p)^4p$$

$$\frac{d}{dp}[4ln(1-p) + ln(p)] = \frac{-4}{1-p} + \frac{1}{p}$$

So, the ML estimate (MLE) is $\widehat{p} = \frac{1}{5} = 0.20$

Per <u>p.119</u>, <u>ex. 3.71</u>, for Y a Geometric RV with success probability p, we have (a) P(Y > a) = q^a, and so (b) the memory-less property: P(Y > a + b | Y > a) = P(Y > b)

- Related to the GEO distribution is the Negative Binomial NB distribution which waits for the rth success
- For y ≥ r, if the rth success occurs on trial y, then we know that (r-1) successes occurred on trials 1 to (y-1), and this latter event is binomial this leads to the following probability function for the NB distribution:

$$p(y) = {y-1 \choose r-1} p^r q^{y-r}; y = r, r+1, r+2 ..., 0 \le p \le 1$$

- <u>p.122, ex.3.14</u>: drilling oil wells with p = 0.2, r = 3, then $p(5) = {5-1 \choose 3-1} (0.2)^3 (0.8)^2 = 0.0307$
- The R command for the previous calculation is "dnbinom(y₀-r,r,p)" or here "dnbinom(2,3,0.2)"
- Not requested, but note that the R command "pnbinom(2,3,0.2)" is equivalent to "dnbinom(0,3,0.2) + dnbinom(1,3,0.2) + dnbinom(2,3,0.2)"
- For a NB random variable with parameters p and r,

$$\mu = E(Y) = \frac{r}{p} \text{ and } \sigma^2 = V(Y) = \frac{r(1-p)}{p^2}$$

• For <u>ex.3.14</u>, $\mu = 3/0.2 = 15$ and $\sigma^2 = 3(0.8)/(0.2)^2 = 60$.

Section 3.7

 The Hypergeometric HG distribution can be thought of as a 'sampling without replacement' analog of the Binomial distribution; the population size is N, and r are of one type (A) and the remaining (N-r) the other type (B). Thus, the proportion of the type A objects is p = r/N, and we take a sample (without replacement) of size n. Y is the number of type A objects.

• The probability distribution for a HG RV (Y) is

$$p(y) = \frac{\binom{r}{y} \binom{N-r}{n-y}}{\binom{N}{n}}$$

- Constraints on y above are: y ≥ n+r-N and y≤r
- <u>p. 126, ex.3.16</u>: N = 20, n = 10, r = y = 5,

$$p(5) = \frac{\binom{5}{5}\binom{15}{5}}{\binom{20}{10}} = 0.0163$$

- In R, instead of "choose(15,5)/choose(20,10)", we can just use "dhyper(y₀,r,N-r,n)" here "dhyper(5,5,15,10)"
- Y is a HG RV, then the mean and variance are

$$\mu = E(Y) = \frac{nr}{N}$$
 and $\sigma^2 = V(Y) = n\left(\frac{r}{N}\right)\left(\frac{N-r}{N}\right)\left(\frac{N-n}{N-1}\right)$

- Note that $\mu = np$, and denoting the factor $\frac{N-n}{N-1}$ as ϕ , we get $\sigma^2 = np(1-p)\phi$, similar to a BIN RV
- For given n, as $N \to \infty$, we get $\phi \to 1$, whence both the mean and variance coincide with BIN dist.; so too do the probability functions coincide since $N \to \infty$ means an infinite population in which case sampling with and without replacement are essentially the same.

- p.127, ex.3.17: N = 20, n = 5, p = 4/20 = 0.2, and we reject if Y > 1, so p(Y > 1) = 1 p(0) p(1) = 0.2487; also, μ = 5*0.20 = 1, σ ² = 5*0.20*0.80*(15/19) = 0.6316
- In R: "1-phyper(1,4,16,5)" yields "0.24871"

- The Poisson POI distribution is related to the BIN distribution as derived on p.131: for the number of occurrences of some event over a time interval, we break the interval to n equal-length sub-intervals so that occurrences on the sub-intervals are independent and p(0) = 1-p, p(1) = p, and p(2 or more) = 0
- Here, p is the probability of an occurrence (a 'success') on any sub-interval
- Then the total number of occurrences on the larger interval has the POI distribution with mean $\lambda = np$
- The POI probability function with parameter λ is

$$p(y) = \frac{\lambda^y}{y!} e^{-\lambda} \text{ for } y = 0, 1, 2 \dots \text{ and } \lambda > 0$$

- In our derivations, recall that $\lim_{n \to \infty} \left(1 + \frac{k}{n}\right)^n = e^k$ and that $e^k = \sum_{z=0}^\infty \frac{k^z}{z!} = 1 + \frac{k}{1} + \frac{k^2}{2} + \frac{k^3}{6} + \frac{k^4}{24} + \cdots$
- For a given problem or exercise, always note the [larger] interval length (see ex. 3.22 below)

- <u>p.132</u>, <u>ex.3.19</u>: Per 30-minute period, $\lambda = 1$ (one visit per half-hour period), so $p(y) = \frac{1}{y!}e^{-1}$ and $p(0) = e^{-1}/1 = 0.368$, $p(1) = e^{-1}/1 = 0.368$, and $p(2) = e^{-1}/2 = 0.1839$; $P(Y \ge 1) = 1 p(0) = 1 e^{-1} = 0.6321$
- In R, "dpois(2,1)" gives "0.1839397", and for P(Y ≥ 1), typing "1-ppois(0,1)" yields "0.6321206"
- p.134, ex.3.21 demonstrates that the POI distribution can provide a good approximation to the BIN <u>for large</u> n & small p: the exact BIN answer is pbinom(3,20,0.1) = 0.8670467, and POI gives ppois(3,2) = 0.8571235.
- p. 134, Theorem 3.11 states that for Y a POI RV with parameter λ , $\mu = \sigma^2 = \lambda$. Again, proofs are important.
- p.135, ex.3.22 (Poisson Process): average is stated as 3 accidents per month, but since the rest of the exercise concerns 2-month period, take $\lambda = 2(3) = 6$ (accidents per 2-month period). We obtain the desired P(Y \geq 10) using R: 1-ppois(9,6) = 0.08392402. Since this p-value is not unusually small, we can conclude that 10 accidents in the past 2 months is not indicative that the mean has increased (from old mean of $\lambda = 6$).

 We define a function, called the moment generating function, MGF, which can be used to obtain (generate) the moments of a distribution. At this point, the MGF appears only theoretical, but we will find it very useful later to identify the distribution of a given RV.

- p.138, <u>Definition 3.12</u>: The k^{th} moment of the RV Y about the origin or about zero is $\mu'_k = E(Y^k)$
- p.138, <u>Definition 3.13</u>: The kth moment of Y *about its* mean or central moment is $\mu_k = E[(Y \mu)^k]$
- Thus, $\mu_1' = \mu$, $\mu_2' = E(Y^2) = \sigma^2 + \mu^2$, $\mu_1 = 0$, and $\mu_2 = \sigma^2$; other moments (such as skewness and kurtosis) can also be calculated.
- p.139, <u>Definition 3.14</u>: The MGF, m(t), for a RV Y is m(t) = E(e^{tY}) provided there exists a positive constant b such that m(t) is finite for |t| ≤ b
- Provided m(t) exists, it's easy to show that (see p.139)

$$m(t) = E(e^{tY}) = 1 + t\mu'_1 + \frac{t^2}{2!}\mu'_2 + \frac{t^3}{3!}\mu'_3 + \cdots$$

• p.139, <u>Theorem 3.12</u>: If m(t) exists, then for any positive integer k,

$$\left. \frac{d^k m(t)}{dt^k} \right|_{t=0} = m^{(k)}(0) = \mu'_k$$

That is, the k^{th} derivative of m(t) with respect to t and evaluated at t = 0 gives μ'_k .

• It is shown (p.140, ex.3.23; p.142, ex.3.145; and p.142, ex.3.147) that the MGFs for the Poisson, Binomial and Geometric distributions are as follows (center column):

Distribution	MGF	PGF
Poisson	$m(t) = e^{\lambda(e^t - 1)}$	p.146 ex.3.165
Binomial	$m(t) = (pe^t + q)^n$	p.146 ex.3.164
Geometric	$m(t) = \frac{pe^t}{1 - qe^t}$	$\pi(t) = \frac{pt}{1 - qt}$

- For the GEO MGF, it is necessary that qe^t < 1, i.e., that t < -ln(q). Since there is an interval around zero for which E(e^{tY}) exists, m(t) is indeed well-defined.
- <u>p.141, ex.3.24</u>: For a Poisson RV, $m(t) = e^{\lambda(e^t 1)}$, so $m'(t) = \lambda e^t e^{\lambda(e^t 1)}$ so $\mu = m'(0) = \lambda$ and $m''(t) = \lambda \left[\lambda e^{2t} e^{\lambda(e^t 1)} + e^t e^{\lambda(e^t 1)}\right]$ thus $\mu'_2 = m''(0) = \lambda(\lambda + 1) = \lambda^2 + \lambda$. So, $\sigma^2 = \lambda^2 + \lambda \lambda^2 = \lambda$.
- <u>p.141</u>, <u>ex.3.25</u>: If Y is a RV with MGF $m(t) = e^{3.2(e^t 1)}$, then we know it has a Poisson distribution with mean $\lambda = 3.2$. That is, we can identify the distribution by the <u>uniqueness property</u> of MGFs.

p.144, <u>Definition 3.15</u>: For the discrete RV Y, let P(Y=k) be denoted p_k for k=0,1,2,..., then for all t such that it is finite, the <u>probability generating function PGF</u> of Y is

$$\pi(t) = E(t^Y) = \sum_{k=0}^{\infty} p_k t^k$$

 p.144, <u>Definition 3.16</u>: For the RV Y and k a positive integer, the kth factorial moment is

$$\mu_{[k]} = E(Y^{(k)}) = E[Y(Y-1)(Y-2)...(Y-k+1)]$$

• p.144, Theorem 3.13: If $\pi(t)$ is the PGF for the integer-valued RV Y, then we can obtain factorial moments by:

$$\left. \frac{d^k \pi(t)}{dt^k} \right|_{t=1} = \pi^{(k)}(1) = \mu_{[k]}$$

- <u>p.145</u>, ex.3.26: For GEO and t < 1/q, $\pi(t) = \frac{pt}{1-qt}$
- <u>p.145, ex.3.27</u>: From above, $\pi'(t) = p(1-qt)^{-2}$, so $\pi'(1) = p/(1-q)^2 = 1/p$. Also, $\pi''(t) = 2pq(1-qt)^{-3}$, so $\mu_{[2]} = 2q/p^2$

Section 3.11

- Empirical Rule: For distributions that resemble the Normal distribution, approximately 68%, 95% and 99.7% are within 1, 2 and 3 σ 's of μ .
- For <u>any distribution</u>, however, Chebyshev's theorem gives a lower bound: for constant k > 0,

$$P(|Y - \mu| < k\sigma) \ge 1 - \frac{1}{k^2}$$

Equivalent to the above is:

$$P(|Y - \mu| \ge k\sigma) \le \frac{1}{k^2}$$

• Thus, for any distribution, <u>lower bounds</u> to the coverage within 1, 2 and 3 σ 's of μ are: 0, 75% & 88.9%